

Space Physics - Problem Sheet 2 Solutions

Question 1

1a) The equation of motion of the particle is (as $E = 0$)

$$m \frac{d\mathbf{v}}{dt} = q \mathbf{v} \times \mathbf{B} \quad (1.1)$$

and the three equations for the components of \mathbf{v} are:

$$\frac{dv_x}{dt} = \frac{qB}{m} v_y \quad (1.2)$$

$$\frac{dv_y}{dt} = -\frac{qB}{m} v_x \quad (1.3)$$

$$\frac{dv_z}{dt} = 0 \quad (1.4)$$

Take derivative of (1.2):

$$\begin{aligned} \frac{d^2v_x}{dt^2} &= \frac{qB}{m} \frac{dv_y}{dt} + \frac{q}{m} v_y \frac{dB}{dt} \\ &= \frac{qB}{m} \frac{dv_y}{dt} + \frac{q}{m} v_y \frac{dB}{dy} \frac{dy}{dt} \end{aligned}$$

and since $\frac{dy}{dt} = v_y$, we get

$$\frac{d^2v_x}{dt^2} = \frac{qB}{m} \frac{dv_y}{dt} + \frac{q}{m} v_y^2 \frac{dB}{dy} \quad (1.5)$$

Take derivative of (1.3):

$$\begin{aligned} \frac{d^2v_y}{dt^2} &= -\frac{qB}{m} \frac{dv_x}{dt} - \frac{q}{m} v_x \frac{dB}{dt} \\ &= -\frac{qB}{m} \frac{dv_x}{dt} - \frac{q}{m} v_x \frac{dB}{dy} \frac{dy}{dt} \\ &= -\frac{qB}{m} \frac{dv_x}{dt} - \frac{q}{m} v_x v_y \frac{dB}{dy} \quad (1.6) \end{aligned}$$

Substitute (1.3) into the first term on the RHS of (1.5)

$$\frac{d^2v_x}{dt^2} = -\left(\frac{qB}{m}\right)^2 v_x + v_y^2 \frac{q}{m} \frac{dB}{dy} \quad (1.7) \quad (2)$$

which is the equation (1) you were asked to derive. On substituting (1.2) into first term on RHS of (1.6) :

$$\frac{d^2v_y}{dt^2} = -\left(\frac{qB}{m}\right)^2 v_y - v_x v_y \frac{q}{m} \frac{dB}{dy} \quad (1.8)$$

which is equation (2) from the question, and equation (3) in the question was derived right at the start of the solution is (1.4)

1b) Substitute the Taylor expansion $B(y) = B_0 + (y-y_0) \frac{dB}{dy}$ into the expression $(qB/m)^2$, to get

$$\left(\frac{q}{m}\right)^2 \left[B_0 + (y-y_0) \frac{dB}{dy} \right]^2 \approx \left(\frac{q}{m}\right)^2 \left[B_0^2 + 2B_0(y-y_0) \frac{dB}{dy} \right]$$

where we have neglected the second order term in $(dB/dy)^2$. Using this result in (1.7) gives

$$\frac{d^2v_x}{dt^2} + \left(\frac{qB_0}{m}\right)^2 v_x = -\frac{2q}{m} \left[\frac{q}{m} B_0 (y-y_0) v_x - \frac{v_y^2}{2} \right] \frac{dB}{dy} \quad (1.9)$$

On the RHS of (1.9) we can substitute the expressions derived in the course for v_x, v_y and $(y-y_0)$:

$$v_x = U_\perp \sin(\Omega t) \quad (1.10) \quad , \quad v_y = U_\perp \cos(\Omega t) \quad (1.11)$$

where $\Omega = \frac{qB_0}{m}$ and $U_\perp^2 = v_x^2 + v_y^2$;

$$y - y_0 = \int v_y dt = \frac{U_\perp}{\Omega} \sin(\Omega t) \quad (1.12)$$

$$\text{Calculate } (y-y_0)v_x = \frac{U_\perp^2}{\Omega} \sin^2(\Omega t) = \frac{U_\perp^2}{2\Omega} [1 - \cos(2\Omega t)] \quad (1.13)$$

$$\text{Similarly } v_y^2 = U_\perp^2 \cos^2(\Omega t) = \frac{1}{2} U_\perp^2 [1 + \cos(2\Omega t)] \quad (1.14)$$

Substituting (1.13), (1.14) into (1.9) gives

$$\frac{d^2v_x}{dt^2} + \left(\frac{qB_0}{m}\right)^2 v_x = -\frac{q}{m} \frac{v_{1x}^2}{z} \frac{dB}{dy} [1 - 3\cos(2nt)] \quad (1.15) \quad (3)$$

which is equation (4) from the question which we were asked to derive.

Using the result for the Taylor expansion for $(qB/m)^2$ in (1.8) gives

$$\frac{d^2v_y}{dt^2} + \left(\frac{qB_0}{m}\right)^2 v_y = -\frac{2q}{m} \left[\frac{qB_0}{m} (y-y_0) v_y + \frac{1}{2} v_{xy} v_y \right] \frac{dB}{dy} \quad (1.16)$$

Using (1.10), (1.11) and (1.12) we get:

$$(y-y_0) v_y = \frac{v_{1x}^2}{n^2} \sin(nt) \cos(rt) = \frac{1}{2} \frac{v_{1x}^2}{n^2} \sin(2nt) \quad (1.17)$$

$$\text{Similarly } v_{xy} = v_{1x}^2 \sin(nt) \cos(rt) = \frac{1}{2} \frac{v_{1x}^2}{n^2} \sin(2nt) \quad (1.18)$$

Substituting (1.17) and (1.18) into (1.16) we get:

$$\frac{d^2v_y}{dt^2} + \left(\frac{qB_0}{m}\right)^2 v_y = -\frac{3}{2} \frac{q}{m} \frac{v_{1x}^2}{z} \frac{dB}{dy} \sin(2nt) \quad (1.19)$$

1c) Equations (1.15) and (1.19) are those given as (4) and (5) in the question. The first term of the solution of (1.15) is obtained from

$$\frac{d^2v_x}{dt^2} + \left(\frac{qB_0}{m}\right)^2 v_x = 0 \quad \text{and it is given in}$$

(1.10) : $v_x = v_{1x} \sin(nt)$. The particular solution of (1.15) is obtained by setting $\frac{d^2v_x}{dt^2} = 0$, so that

$$\left(\frac{qB_0}{m}\right)^2 v_{2x} = -\frac{q}{m} \frac{v_{1x}^2}{z} \frac{dB}{dy} [1 - 3\cos(2nt)]$$

or $v_{2x} = -\frac{q}{m} \left(\frac{m}{qB_0}\right)^2 \frac{v_{1x}^2}{z} \frac{dB}{dy} [1 - 3\cos(2nt)]$ so that the complete solution is:

$$v_{2x} = v_{1x} \sin(nt) - \frac{1}{q} \frac{m v_{1x}^2}{z B_0^2} \frac{dB}{dy} [1 - 3\cos(2nt)] \quad (1.20)$$

Similarly to find the solution of the homogeneous part of equation (1.19) :

$$\frac{d^2 u_y}{dt^2} + \left(\frac{qB_0}{m}\right)^2 = 0, \quad (4)$$

$u_y = v_L \cos(\nu t)$... The particular solution of the complete equation is obtained from:

$$\left(\frac{qB_0}{m}\right)^2 u_y = -\frac{3}{2} \frac{q}{m} v_L^2 \frac{dB}{dy} \sin(2\nu t)$$

$$\text{and we get: } u_y = -\frac{3}{2} \left(\frac{q}{m}\right) \left(\frac{m}{qB_0}\right)^2 v_L^2 \frac{dB}{dy} \sin(2\nu t)$$

so that the complete solution of equation (1.19) is:

$$u_y = v_L \cos(\nu t) - \frac{3}{q} \frac{mv_L^2}{2B_0^2} \frac{dB}{dy} \sin(2\nu t) \quad (1.21)$$

(d) The displacement of the particle in one gyroperiod can be calculated as:

$$\Delta x_T = \int_0^T u_x dt, \quad \Delta y_T = \int_0^T u_y dt \quad \text{where}$$

$$T = \frac{2\pi}{\nu} = \frac{2\pi m}{qB}$$

Write Δx_T explicitly:

$$\Delta x_T = \int_0^T v_L \sin(\nu t) dt - \int_0^T \frac{1}{q} \frac{mv_L^2}{2B_0^2} \frac{dB}{dy} [1 - 3\cos(2\nu t)] dt$$

The terms $\sin(\nu t)$ and $\cos(2\nu t)$ integrate to 0 over a gyroperiod, since $\nu = 2\pi/T$, so that

$$\Delta x_T = - \int_0^T \frac{1}{q} \frac{mv_L^2}{2B_0^2} \frac{dB}{dy} dt = -\frac{1}{q} \frac{mv_L^2}{2B_0^2} \frac{dB}{dy} T$$

For Δy_T we have

$$\Delta y_T = \int_0^T v_L \cos(\nu t) dt - \int_0^T \frac{3}{q} \frac{mv_L^2}{2B_0^2} \frac{dB}{dy} \sin(2\nu t) dt$$

Both terms integrate to 0, so that $\Delta y_T = 0$ and the average velocities are therefore:

$$\langle U_x \rangle = \frac{\Delta x_r}{T} = -\frac{1}{q} \frac{m v_{\perp}^2}{2B_0^2} \frac{dB}{dy}, \quad \langle U_y \rangle = 0$$

1e) In the case of the problem as given here, $\underline{B} = B_0 \hat{z}$ and $D\underline{B} = (\frac{dB}{dy}) \hat{y}$, so that

$$\underline{B} \times D\underline{B} = -B \left(\frac{dB}{dy} \right) \hat{x}$$

In the first approximation, $\underline{B} = B_0 \hat{z}$ at the particle's gyrocentre, so that

$$U_{\text{gyrod}} = \frac{m v_{\perp}^2}{2q B_0^3} \underline{B} \times D\underline{B} = -\frac{m v_{\perp}^2}{2q B_0^2} \left(\frac{dB}{dy} \right) \hat{x}$$

as found above.

1f.) The general formula for drift velocity due to a force F is

$$U_F = \frac{1}{qB^2} \underline{F} \times \underline{B}$$

Comparing this with the expression for the drift velocity due to $D\underline{B}$ gives

$$F_{\text{gyrod}} = -\frac{m v_{\perp}^2}{2B} D\underline{B}$$

Question 2

2a) A particle gyrating around the magnetic field B has a gyroradius

$$r_c = \frac{v_{\perp}}{\omega} = \frac{m v_{\perp}}{qB}, \quad \text{where } \omega = |\underline{\omega}|$$

The current generated by the particle is

$$I = \frac{q \sqrt{2}}{2\pi} = \frac{q^2 B}{2\pi m}$$

that is, the number of times the particle passes through a point on its gyroscopic trajectory (the gyrofrequency) multiplied by the particle's electric charge. The area of the current

is $A = \pi r_L^2$, so that the particle's magnetic moment is

$$m = IA = \frac{q^2 B}{2\pi m} \pi \frac{m^2 v_{\perp}^2}{q^2 B^2} = \frac{mv_{\perp}^2}{2B}$$

2b) As \underline{B} is cylindrically symmetric, with $B_z \neq 0$, then $B_\phi = 0$, and as $\nabla \cdot \underline{B} = 0$, then

$$\frac{1}{r} \frac{\partial}{\partial r} (r B_r) + \frac{\partial B_z}{\partial z} = 0, \text{ or } \frac{\partial}{\partial r} (r B_r) = -r \frac{\partial B_z}{\partial z}$$

Integrating with respect to r gives

$$r B_r = -\frac{r^2}{2} \frac{\partial B_z}{\partial z}, \text{ so that } B_r \approx -\frac{r}{2} \frac{\partial B_z}{\partial z}$$

$$\text{as we assumed } \frac{\partial B_z}{\partial z} \approx \frac{\partial B}{\partial z}$$

2c) The equation of motion of the particle is

$$m \frac{d\underline{v}}{dt} = q \underline{v} \times \underline{B} \quad \text{as we assumed that there is no electric field present.}$$

Using $\underline{B} = B_r \hat{r} + B_z \hat{z}$ so that

$$m \frac{d\underline{v}}{dt} = q B_r \underline{v} \times \hat{r} + q B_z \underline{v} \times \hat{z}$$

The second term on the RHS of this equation leads to the gyromotion of the particle around the z -axis, as we assumed $B_z \gg B_r$. The additional force on the particle arises from the first term on the RHS,

$$F_z = F_z \hat{z} = q B_r \underline{v} \times \hat{r} = q B_r v_{\perp} \hat{z}$$

where v_{\perp} is the velocity of the particle perpendicular to \underline{B} , as we assumed that \underline{B} is, to a good approximation, along the z axis. This force F_z acts on the particle at a distance $r = r_c$ from the z -axis (because that's where the particle is!) with r_c being the gyroradius of the particle. We have, at $r = r_c$

$$F_z = qU_L B_r |_{r=R} = -qU_L \frac{1}{2} \frac{\partial B}{\partial z} \quad (7)$$

with $R = \frac{U_L}{\omega} = \frac{mU_L}{qB}$, so that

$$F_z = -\frac{mU_L^2}{2B} \frac{\partial B}{\partial z} \approx -\frac{mU_L^2}{2B} \frac{\partial B}{\partial z} = -\mu \frac{\partial B}{\partial z}$$

2d) The rate of change of the magnetic field as seen by the moving particle (using the approximation $B_z \approx B$) is

$$\frac{dB}{dt} = \frac{\partial B}{\partial z} \frac{dz}{dt} = U_{||} \frac{\partial B}{\partial z}$$

where $U_{||}$ is the velocity of the particle along $B \approx B_z \hat{z}$

We next calculate the work done on the particle by the force F_z . This is equal to the gain in its kinetic energy in the direction of the force, along z . The work is calculated over one gyroperiod, during which we assume that

$$\frac{\partial B_z}{\partial z} \approx \frac{\partial B}{\partial z} \text{ remains (approximately) constant.}$$

The gyroperiod is

$$T = \frac{2\pi}{\omega} = 2\pi \left(\frac{m}{qB} \right)$$

and the particle travels a distance $U_{||}T$ in the direction of z during T .

$$\delta W = \int_0^T F_z dt = \int_0^{U_{||}T} F_z dz = -\mu \frac{\partial B}{\partial z} U_{||} T = -\mu \frac{\partial B}{\partial z} \frac{dz}{dt} T = -\mu \frac{dB}{dt} T$$

The average rate of energy gain during the motion of the particle along z is

$$\frac{d}{dt} \left(\frac{1}{2} mU_{||}^2 \right) = \frac{\delta W}{T} = -\mu \frac{dB}{dt}$$

2e)

As the total kinetic energy remains constant (no electric field is present), its time derivative is zero:

$$\frac{d}{dt} \left(\frac{1}{2} mU^2 \right) = \frac{d}{dt} \left(\frac{1}{2} mU_L^2 \right) + \frac{d}{dt} \left(\frac{1}{2} mU_{||}^2 \right) = 0 \quad \text{We have from part 2a)}$$

of the question, $m = \frac{mU_L^2}{2B}$, or $\frac{1}{2} mU_{||}^2 = \mu B$, so that

$$\frac{d}{dt} \left(\frac{1}{2} m \mathbf{v}_{\perp}^2 \right) = B \frac{du}{dt} + u \frac{dB}{dt}$$

Together with the result from 2d), we have:

$$\frac{d}{dt} \left(\frac{1}{2} m \mathbf{v}^2 \right) = B \frac{du}{dt} + u \frac{dB}{dt} - u \frac{dB}{dt} = 0$$

which gives $B \frac{du}{dt} = 0$, but as $B \neq 0 \rightarrow \frac{du}{dt} = 0$, so that the magnetic moment is conserved.

2f) In a time varying magnetic field $\underline{B} = B(t) \hat{z}$ an electric field is induced (Faraday's law) which is $\nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t}$. In the plane perpendicular to \underline{B} , and therefore to the z axis, the force acting on the particle is only this induced electric field, therefore the equation of motion is

$$m \frac{d\mathbf{v}_{\perp}}{dt} = q \underline{E}_{\perp}; \text{ taking the dot product with } \underline{v}_{\perp} \text{ gives:}$$

$$m \mathbf{v}_{\perp} \cdot \frac{d\mathbf{v}_{\perp}}{dt} = \frac{d}{dt} \left(\frac{1}{2} m \mathbf{v}_{\perp}^2 \right) = q \underline{E}_{\perp} \cdot \underline{v}_{\perp}$$

2g) Using the result from 2f) above, we have (since $\underline{E} = \underline{E}_{\perp}$)

$$\Delta \left(\frac{1}{2} m \mathbf{v}_{\perp}^2 \right) = \int_0^T q \underline{E} \cdot \underline{v}_{\perp} dt = - \oint q \underline{E} \cdot d\underline{l}$$

as a) $\underline{v}_{\perp} dt = d\underline{l}$, the infinitesimal path length of the particle perpendicular to \underline{B} and

b) the negative sign in front of the last integral arises from the integration (in the right-handed, positive sense) along a complete particle orbit; but the particles orbits in the negative sense (anti-clockwise) for $q > 0$, and in the positive sense (clockwise) for $q < 0$.

2h) The change in energy, during one gyroperiod, is

$$\Delta \left(\frac{1}{2} m \mathbf{v}_{\perp}^2 \right) = - \oint q \underline{E} \cdot d\underline{l} = - q \int_A (\nabla \times \underline{E}) \cdot d\underline{A} = q \int_A \frac{\partial \underline{B}}{\partial t} \cdot d\underline{A}$$

where we used Stokes' theorem and Faraday's law. Here $d\underline{A}$ is the infinitesimal surface element vector perpendicular to \underline{B} or equivalently, to the z axis.

IF we assume that the magnetic field changes by an amount ΔB during one gyration of the particle, then we can substitute $\frac{\partial \underline{B}}{\partial t} \approx \frac{\Delta \underline{B}}{T}$ in the integral (noting also that $d\underline{A}$ is parallel to \underline{B}),

so that

$$\Delta \left(\frac{1}{2} m v_{\perp}^2 \right) = q \frac{\Delta B}{T} A$$

where $A = \pi r_L^2 = \pi \left(\frac{v_{\perp} m}{q B} \right)^2$ and $T = 2\pi \frac{m}{q B}$,

substituting for T and A gives;

$$\Delta \left(\frac{1}{2} m v_{\perp}^2 \right) = \mu \Delta B$$

2) By the definition of $\mu = \frac{mv_{\perp}^2}{2B}$, so that

$$\Delta \left(\frac{1}{2} m v_{\perp}^2 \right) = \mu \Delta B + B \Delta \mu = \mu \Delta B \text{ from 2h)$$

and therefore $B \Delta \mu = 0$, and as $B \neq 0$, we have finally

$$\Delta \mu = 0$$

showing that the magnetic moment is conserved also under these assumptions.